

SOC Design of a Neural Network for Real-Time Semantic Segmentation of 2Kx1K@60fps Video

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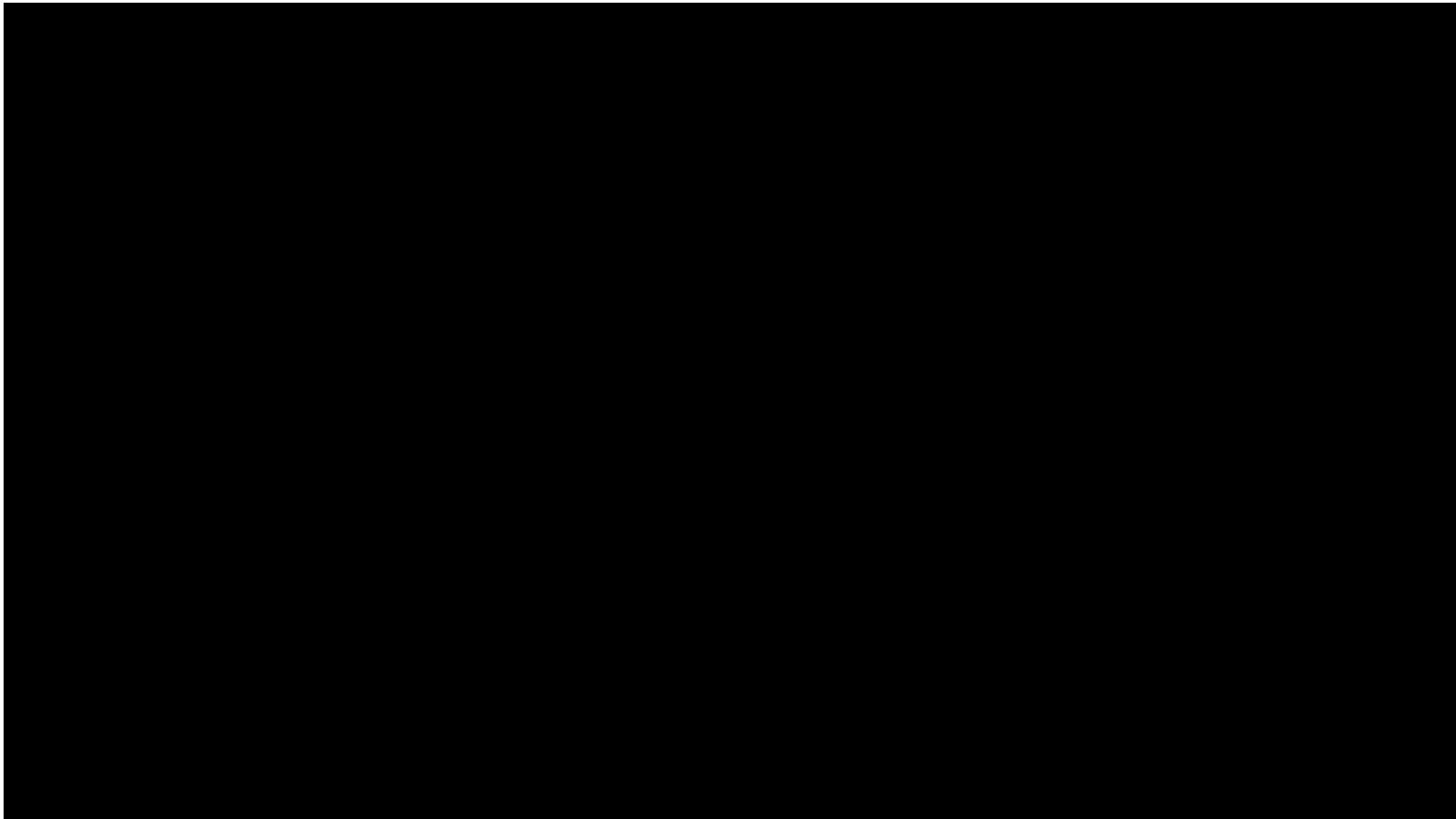
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Project Goals

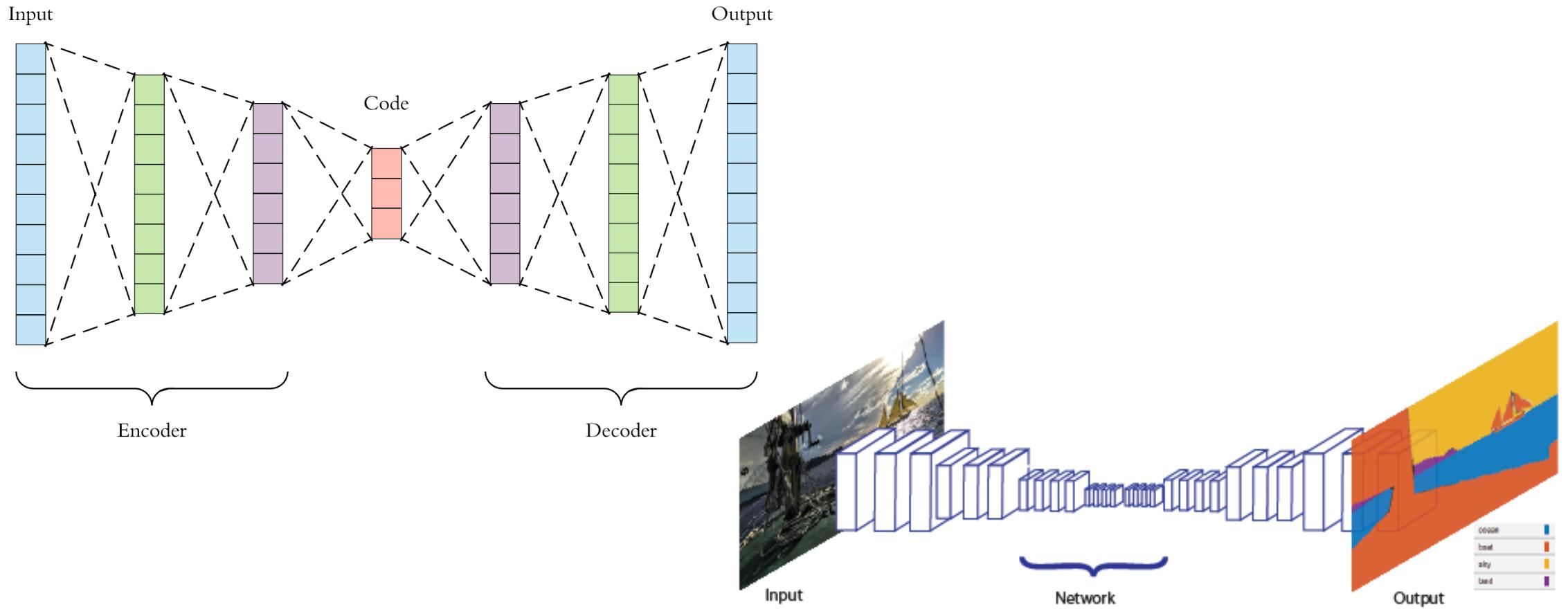
1. Real-time Semantic Segmentation of HD Video (1Kx2K@60fps)
2. Hardware-friendly neural network architecture
3. Proof-of-Concept using GPU
4. ASIC

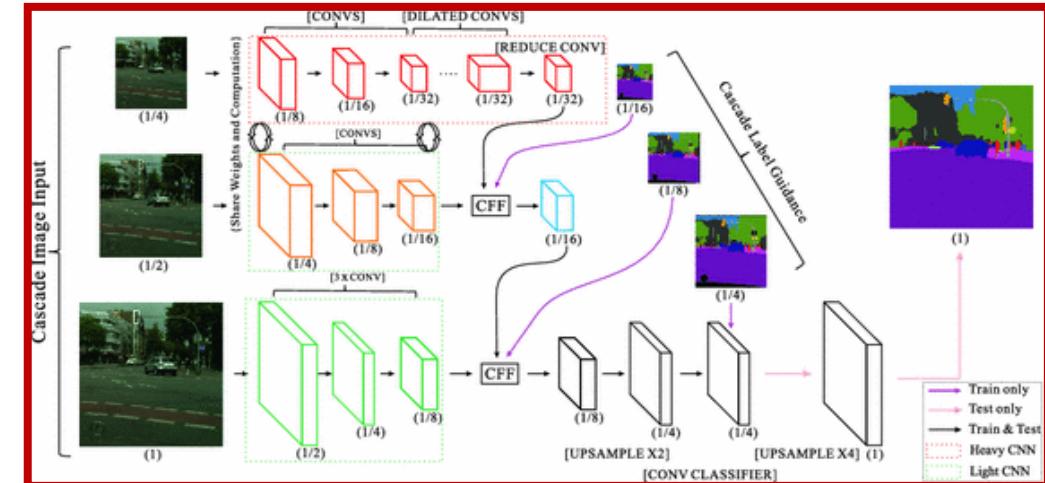
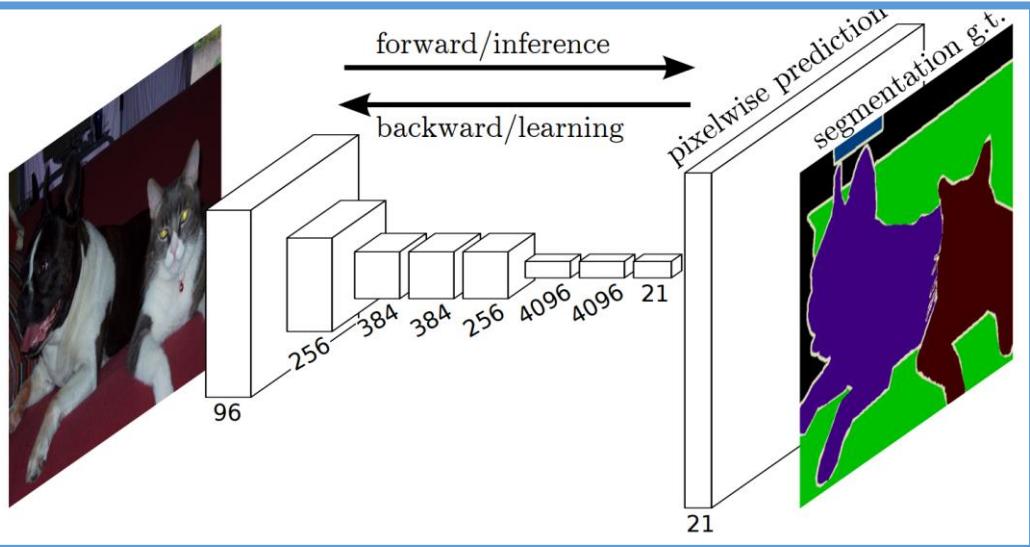


Semantic Segmentation – CityScapes Dataset



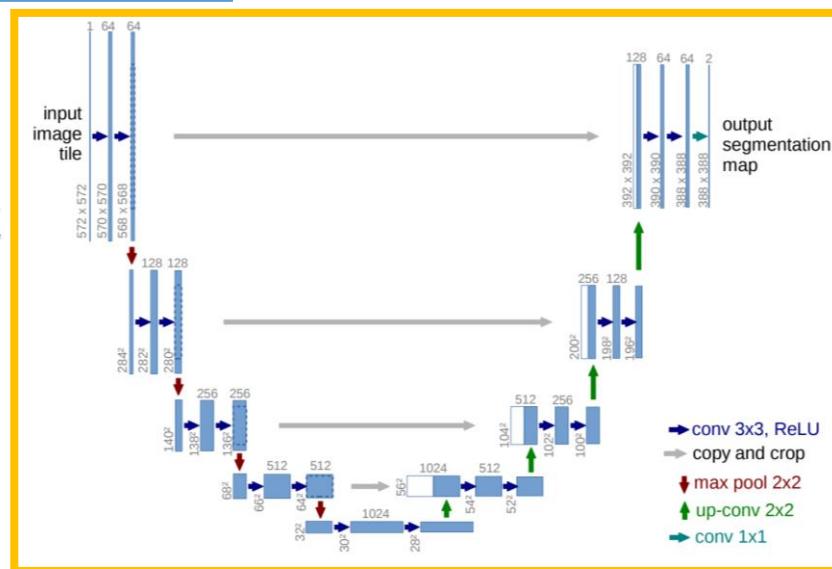
How to do it? Autoencoder, Naturally





FCN

Fully Convolutional Network



ICNet

U-Net

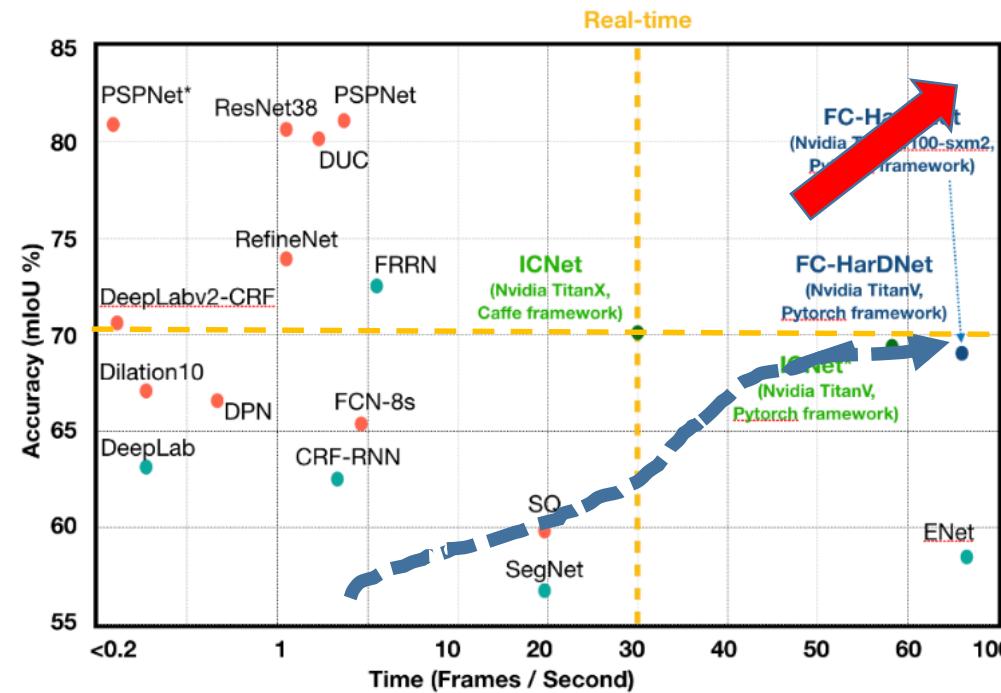
- Long, J., Shelhamer, E., & Darrell, T. (2015). Fully convolutional networks for semantic segmentation. In Proceedings of the IEEE conference on computer vision and pattern recognition (pp. 3431-3440).
 - Ronneberger, O., Fischer, P., & Brox, T. (2015, October). U-net: Convolutional networks for biomedical image segmentation. In International Conference on Medical image computing and computer-assisted intervention (pp. 234-241). Springer, Cham.
 - Zhao, H., Qi, X., Shen, X., Shi, J., & Jia, J. (2018). Icnet for real-time semantic segmentation on high-resolution images. In Proceedings of the European Conference on Computer Vision (ECCV) (pp. 405-420).

What we want for semantic segmentation?

mean IoU
(Intersect over Union)

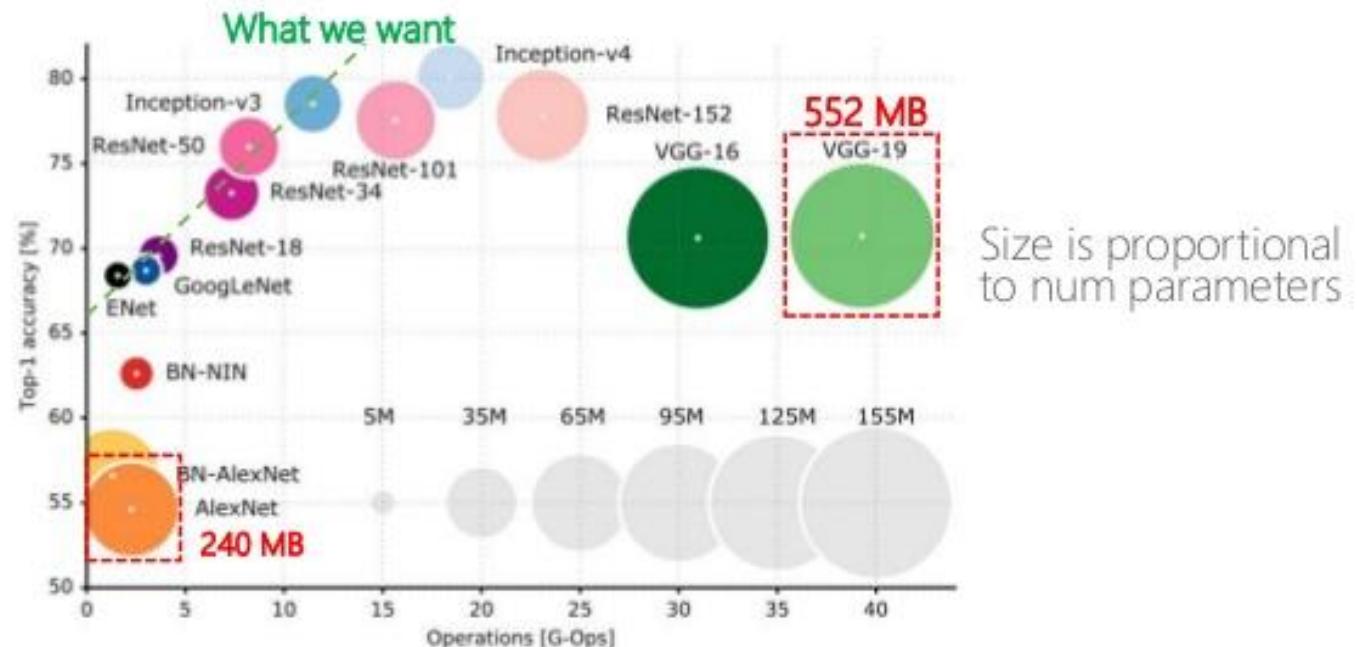


Accuracy vs frames per second



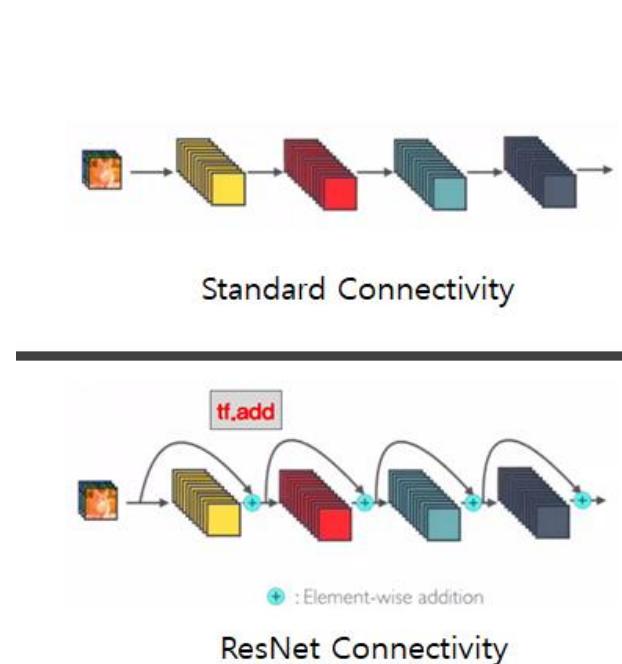
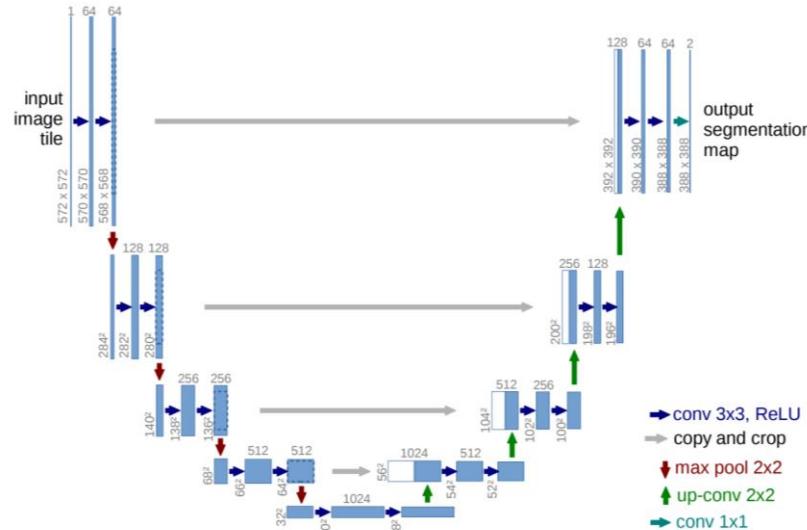
Network design tradeoffs

- Performance (Accuracy) [Accuracy vs Operations Per Image Inference](#)
- Cost
 - Hardware gate count
 - Network size (Parameters)
- Inferencing
 - Time (# Operations?)
 - Energy consumption



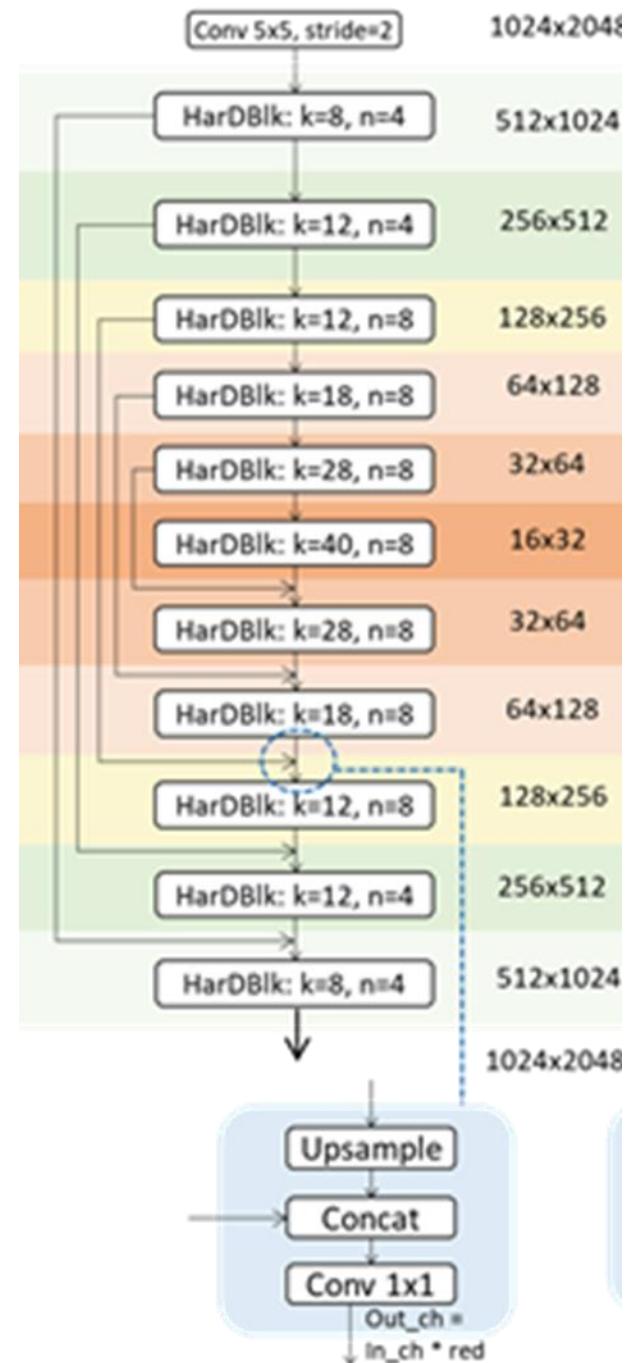
Alfredo Canziani, Adam Paszke, Eugenio Culurciello, "An Analysis of Deep Neural Network Models for Practical Applications" 2016

U-Net & DenseNet-Inspired Network Design



Densely connected convolution networks CVPR 2017 oral presentation slide

Proposed Network



DRAM Traffic vs Run-Time

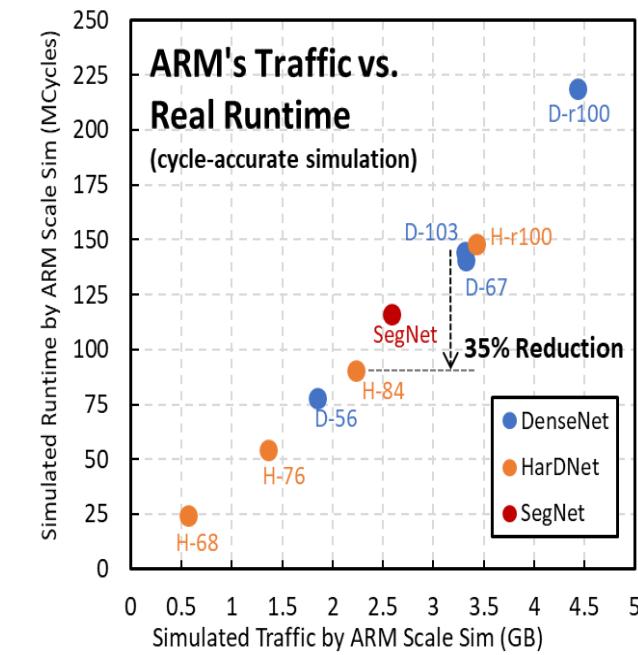
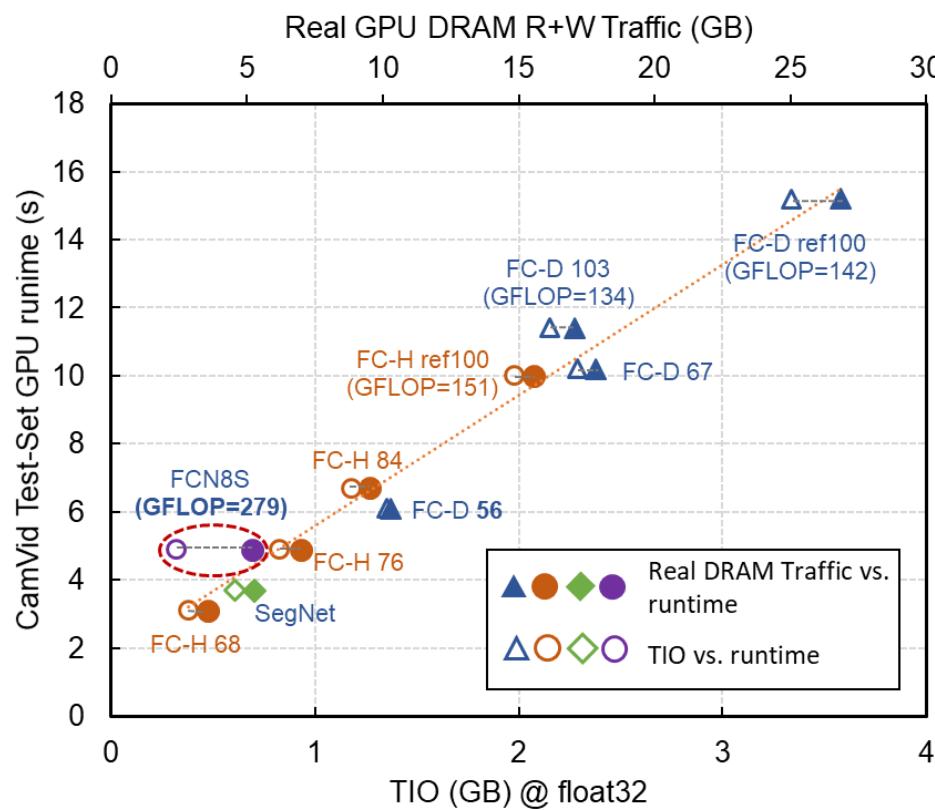
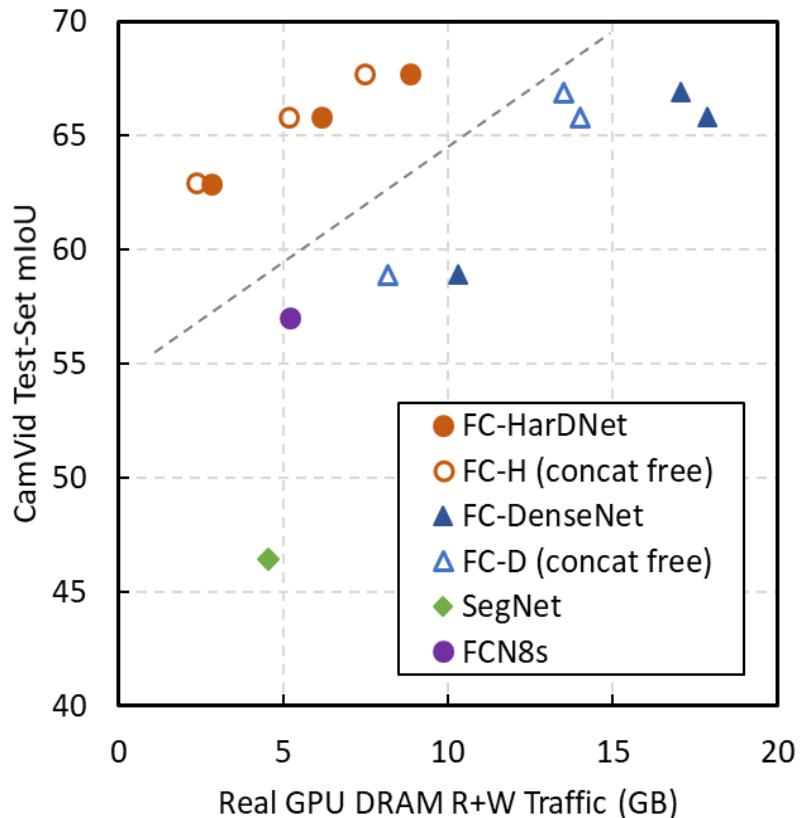


Figure 3: Runtime vs. DRAM traffic measured by the simulation of ARM Scale.

Low DRAM Traffic (Run-Time) and High Accuracy



To make an ASIC

USD8000/300W



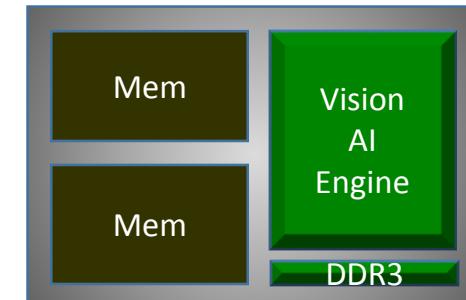
SPECIFICATIONS



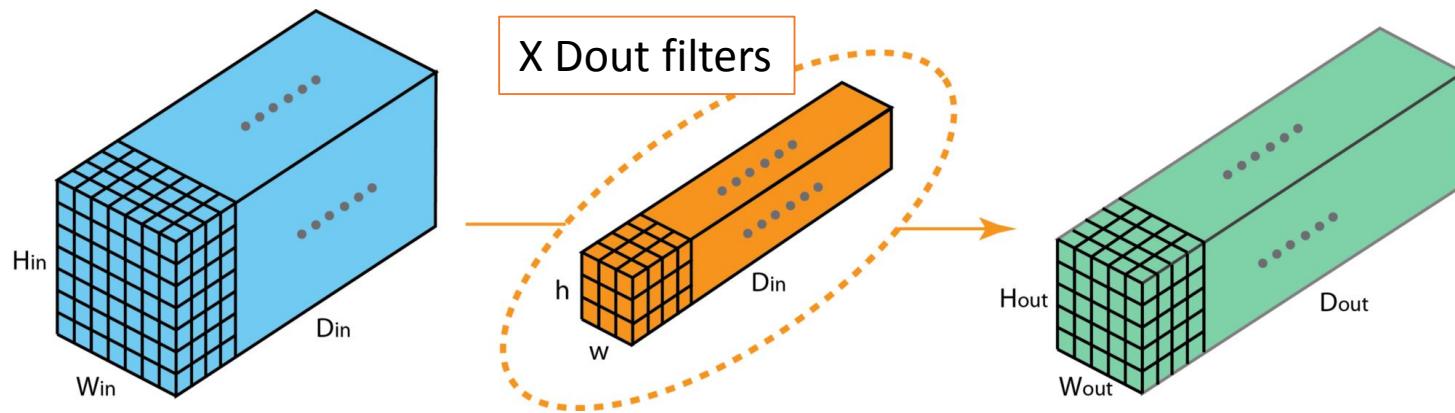
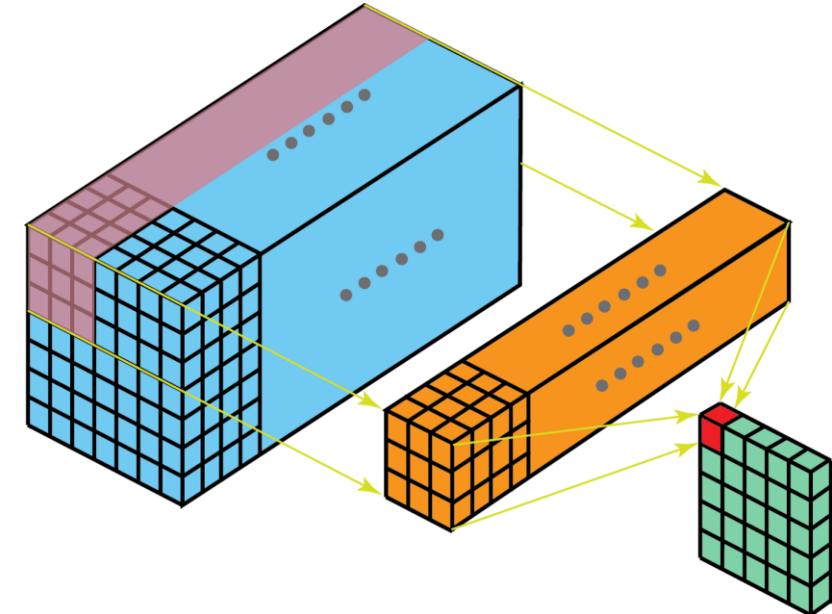
	Tesla V100 PCIe	Tesla V100 SXM2
GPU Architecture	NVIDIA Volta	
NVIDIA Tensor Cores	640	
NVIDIA CUDA® Cores	5,120	
Double-Precision Performance	7 TFLOPS	7.5 TFLOPS
Single-Precision Performance	14 TFLOPS	15 TFLOPS
Tensor Performance	112 TFLOPS	120 TFLOPS
GPU Memory	16 GB HBM2	
Memory Bandwidth	900 GB/sec	
ECC	Yes	
Interconnect Bandwidth*	32 GB/sec	300 GB/sec
System Interface	PCIe Gen3	NVIDIA NVLink
Form Factor	PCIe Full Height/Length	SXM2
Max Power Consumption	250 W	300 W
Thermal Solution	Passive	
Compute APIs	CUDA, DirectCompute, OpenCL™, OpenACC	

USD100/10W

ASIC

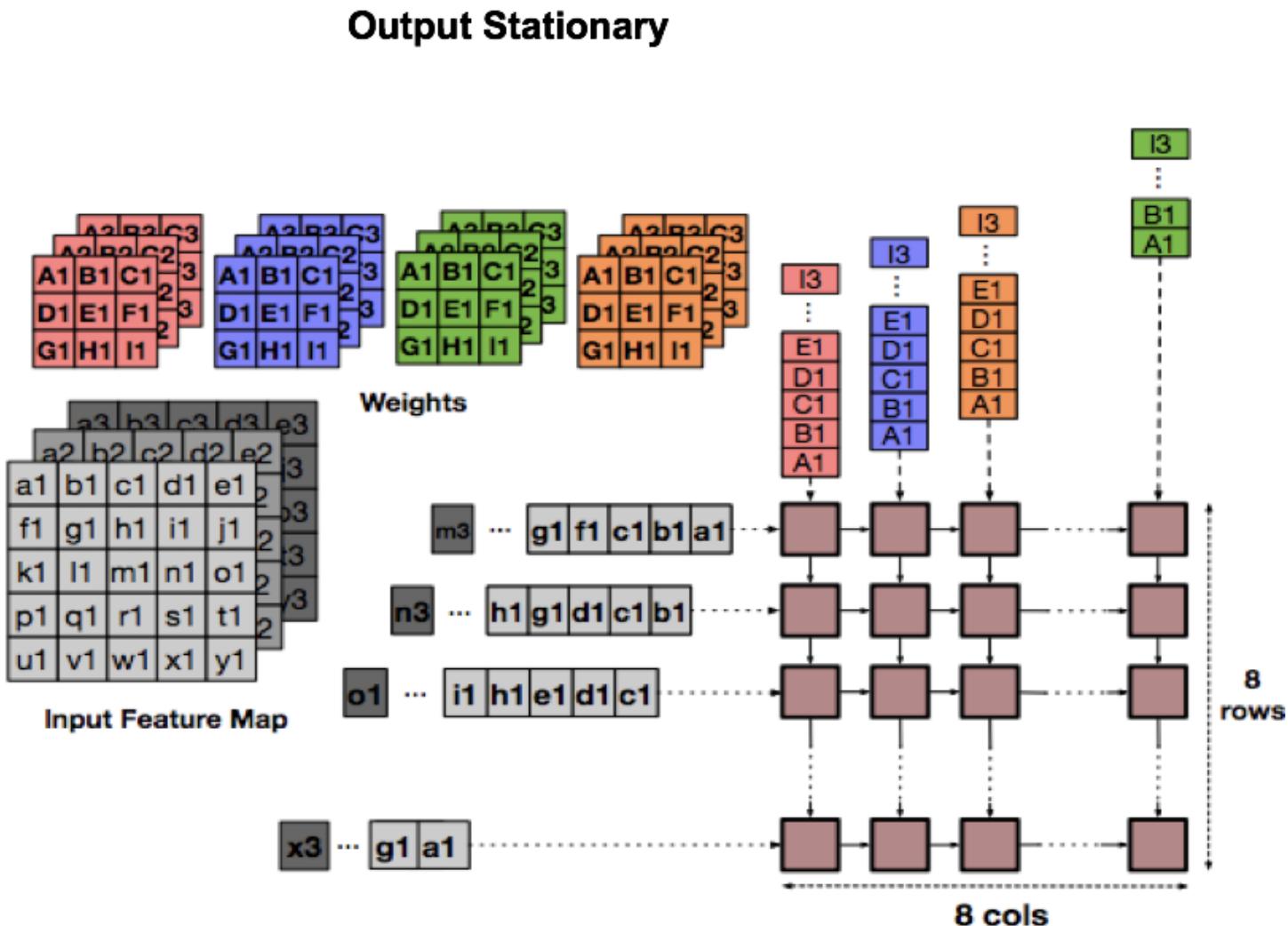


> 99% Computers are 2D Convolution (Multi-Channel, Multi-Filter)



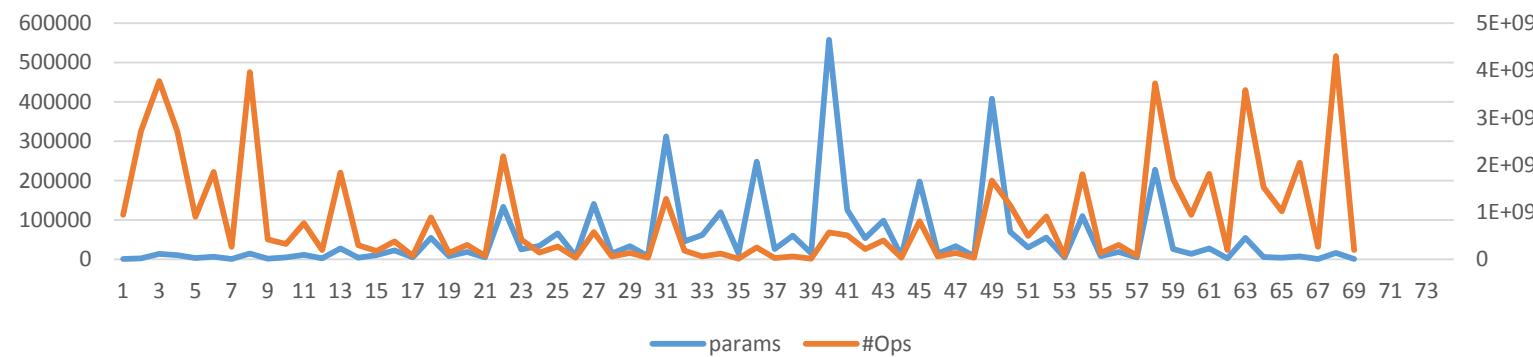
```
for (m = 0; m < numOutputLayers; m++)           //Loop 1
    for (n = 0; n < numInputLayers; n++)          //Loop 2
        for (h = 0; h < outputHeight; h++)         //Loop 3
            for (w = 0; w < outputWidth; w++)       //Loop 4
                for (i = 0; i < kernelHeight; i++)    //Loop 5
                    for (j = 0; j < kernelWidth; j++) //Loop 6
                        out[m][h][w] +=
                            in[n][h * s + i][w * s + j] *
                            kernel[m][n][i][j];
```

2D Convolution with Systolic Array

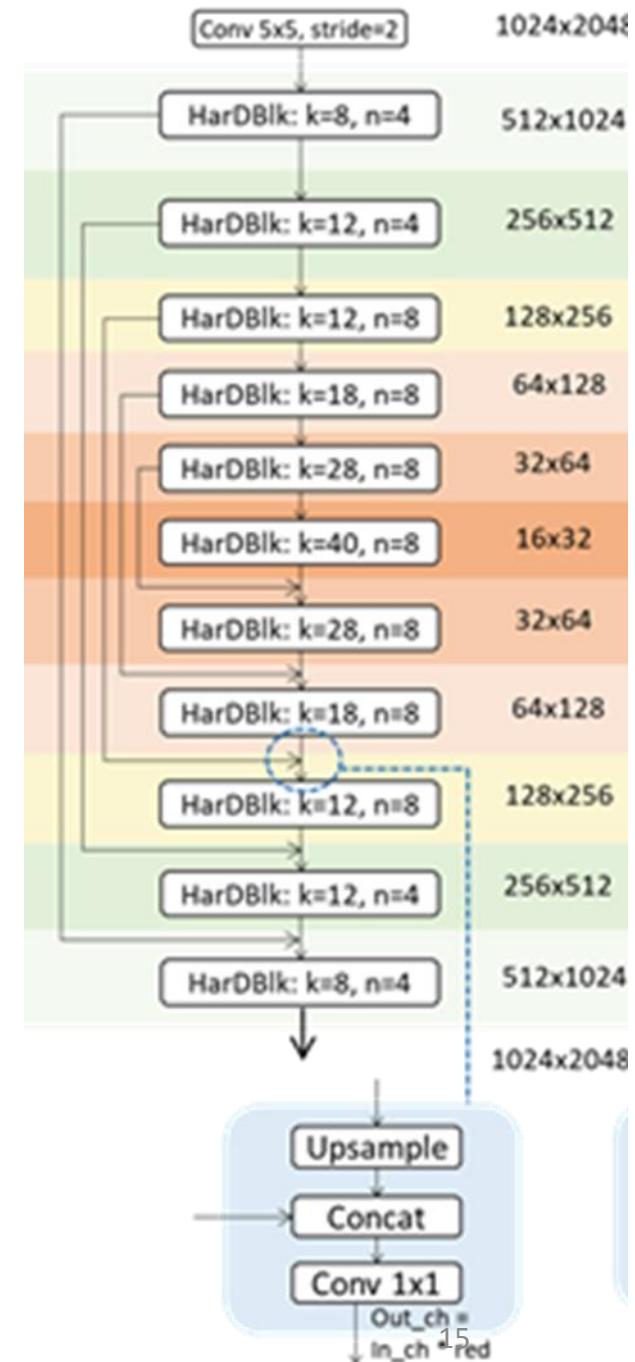
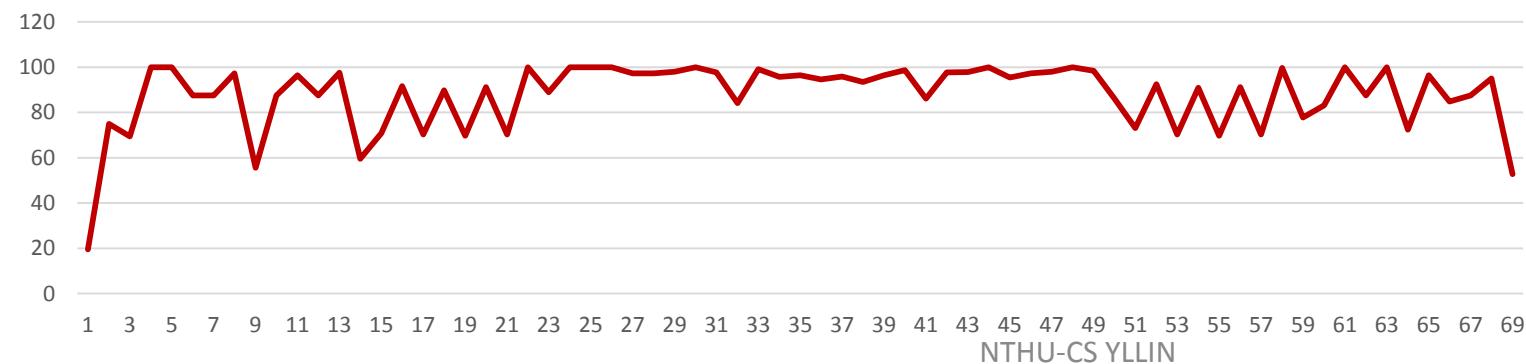


Memory bound vs Compute Bound

Per Layer # Paras vs #Ops



Per Layer Utilization of 9216 MACs



Results

- Network
 - 69-Layer Convolutional Neural Network (Other versions: 84, ...)
 - 3.8M parameters
 - 59.685G Operations per 1Kx2K frame inference
- PyTorch on GPU Implementation
 - 80fps on a TWCC nVidia Tesla V100 32GB GPU (300Watt, USD8,000)
 - $59.658\text{Gops} * 80 / 120\text{Tops}$ **~ 4% utilization**
- Preliminary ASIC Design
 - 9216 MACs (Mutli-Add) = 18,432 PEs
 - Peak performance 9.216 Tera ops @ 500 MHz
 - 3.846M Clock Cycles to inference a 1Kx2K frame
 - $59.685\text{G} / (3.846\text{M} * 18432)$ **~ 85% utilization**

Thank you!!